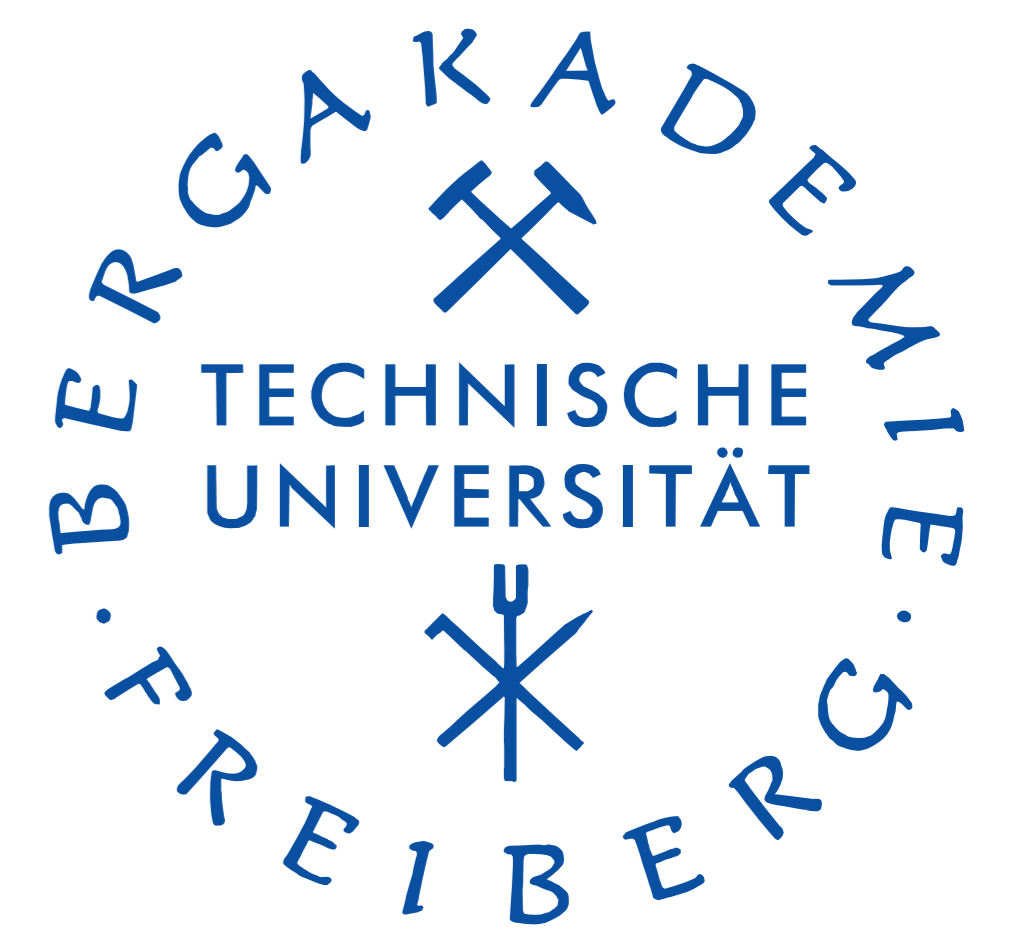


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The Extension Principle Applied to Stochastic Differential Equations

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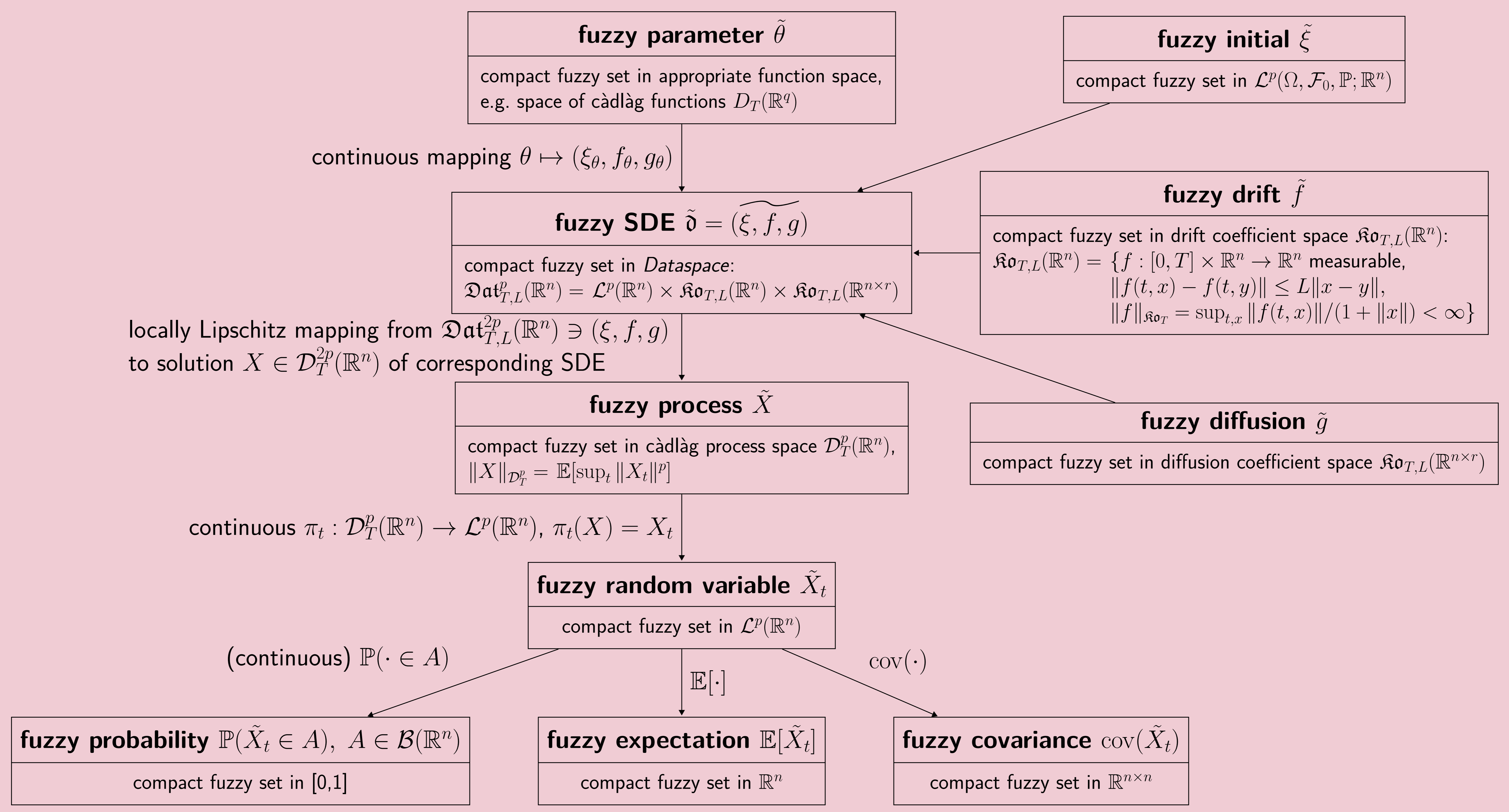
Motivation

- Laws of natural systems are random and imprecise
 - a fox has a random chance to catch a rabbit (**randomness**)
 - the expected hunting performance of the foxes varies over time (**fuzziness**)
- Fuzzy-valued SDEs can only handle crisp diffusion
 - fuzziness of state is neglected in modelling randomness

New Approach

- Use fuzzy sets of mappings for
 - parameters, coefficients (**data**)
 - processes, random variables (**solution**)
 rather than fuzzy-valued mappings
 - no technical problems, great modelling flexibility

General Scheme



Properties

- Beside uncertain range also uncertain behaviour and dependencies between drift and diffusion can be modelled
- Solutions of fuzzy SDEs can be understood as Lipschitz continuous mappings from $[0, T]$ to $\mathcal{F}_k(\mathcal{L}^p(\mathbb{R}^n))$
 - admits time-discrete approximations for e.g. fuzzy expectation $\mathbb{E}[\tilde{X}_t]$

Connections to other approaches

- Solutions of fuzzy SDEs can be interpreted as fuzzy-valued processes with a.s. continuous paths in special cases (additive noise, multiplicative noise, autonomous noise)
- Solutions of fuzzy SDEs are subsets of solution sets of corresponding fuzzy stochastic inclusions (α -cut-wise)

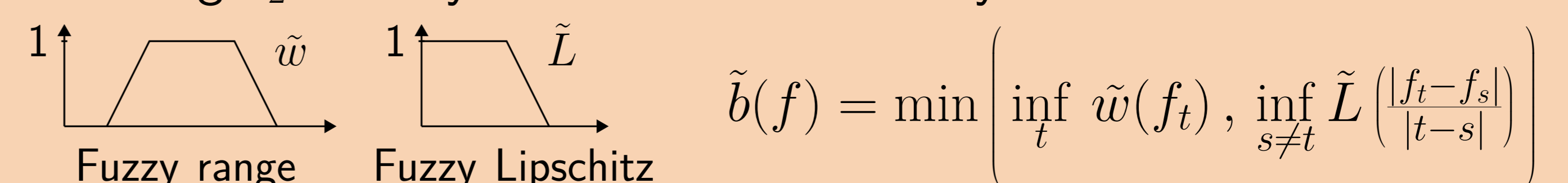
Example

In ecosystems parameters are usually not exactly measurable and vary over time, too. Therefore we consider a stochastic predator-prey system with **uncertain parameters**

$$dX_t = \left(r \frac{k - X_t}{k} - a Y_t \right) X_t dt + \sigma_1 X_t dB_t^{(1)}, \quad X_0 = x_0 \in \mathbb{R},$$

$$dY_t = \left(-m + b_t X_t \frac{Y_t}{z + Y_t} \right) Y_t dt + \sigma_2 Y_t dB_t^{(2)}, \quad Y_0 = y_0 \in \mathbb{R}$$

Modelling $\tilde{\sigma}_2$ as fuzzy number and \tilde{b} as a fuzzy set of continuous functions:



Of interest is the probability of extinction, consider $\mathbb{P}(\tilde{Y}_t < y_{min})$:

