

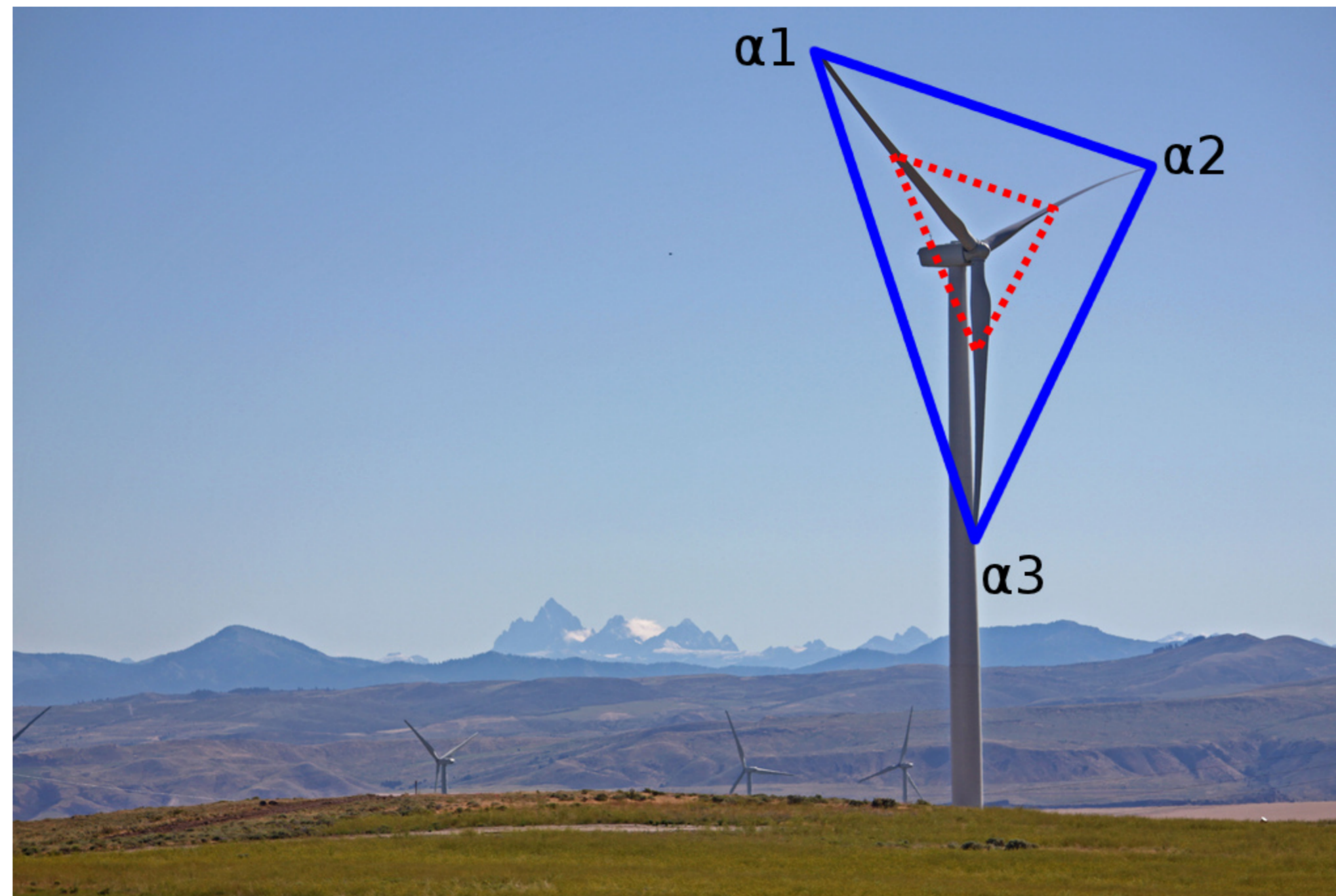
# Modelling Common-Cause Failures Under Severe Prior Uncertainty

Matthias C. M. Troffaes<sup>1</sup> Dana Kelly<sup>2</sup>

<sup>1</sup>Durham University, Department of Mathematical Sciences, UK

<sup>2</sup>Idaho National Laboratory (INL), Nuclear Risk and Reliability Group, US

27 July, 2011



## Example, Model, and Issues

### Example

- adapted from [1]
- three components
- $\alpha_j$ : unknown probability of exactly  $j$  failed components (conditional on at least one failed component)
- $n_j$ : data, counts cases with exactly  $j$  failed components

$\bar{P}(\alpha_1) = 0.950$	$n_1 = 35$
$\bar{P}(\alpha_2) = 0.030$	$n_2 = 1$
$\bar{P}(\alpha_3) = 0.015$	$n_3 = 0$
$\bar{P}(\alpha_4) = 0.005$	$n_4 = 0$

### Alpha Factor Model

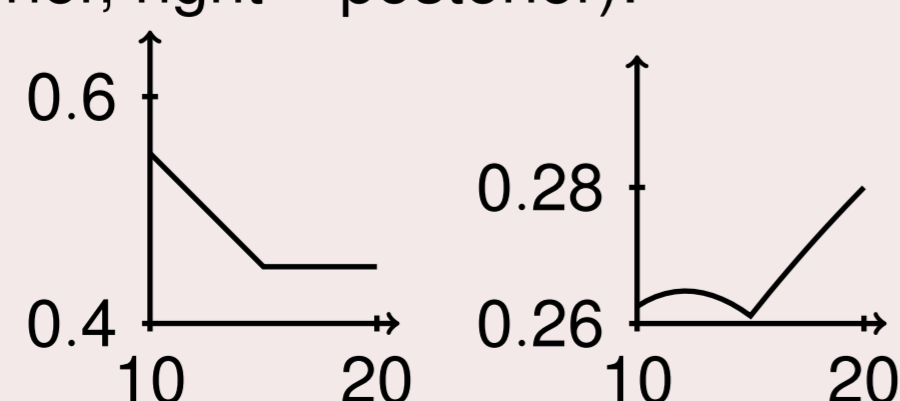
- developed for common cause failures [2]
- multinomial model + conjugate Dirichlet prior
- easily extendable to imprecise case

### How To Pick The Prior?

- posterior sensitive to choice in non-informative prior
- constrained non-informative methods have too light tails
- main problem caused by (close to) zero counts

### Going Imprecise: Arbitrary Set of Dirichlet Priors?

- 'supposedly' simple [4, p. 32, §6]—it's not!
  - **non-linear non-convex optimisation** problems even if prior convex
- example (left = prior, right = posterior):



- **elicitation difficult**, not to say impossible
- need for simpler model without too much sacrifice in precision

## Main Results

### A Simple Generalised IDM Model

- prior set:  $\{(s, \vec{t}) : s \in [s, \bar{s}], t_j \in [t_j, \bar{t}_j]\}$   
 $0 \leq s \leq \bar{s}$   
 $t_j, \bar{t}_j$ : coherent lower and upper probability mass functions
- still non-linear, but convex
- easy to bound an arbitrary set by it
- generalises Walley's general beta-binomial model [3, p. 224, §5.4.3] to multinomial case
- **elicitation is much more straightforward**

### Elicitation Of $t_j$ And $\bar{t}_j$

prior lower and upper probabilities of exactly  $j$  components failing

### Elicitation Of $s$ And $\bar{s}$

- **$s = \bar{s} = 2$  is usually a horrible choice**
  - zero counts have too much influence on the posterior  
higher value of  $s$  needed to increase weight of prior
  - but data *could be* right even for low counts  
prior-data conflict! → lower value of  $s$  to cover also data
- general guideline:
- $\bar{s}$  is the number of one-component failures required to reduce the upper probability  $\bar{t}_j$  ( $j \geq 2$ ) of multi-component failure by half
  - $s$  is the number of multi-component failures required to reduce the lower probability  $t_1$  of one-component failure by half

### References

- [1] Dana Kelly and Corwin Atwood. Finding a minimally informative Dirichlet prior distribution using least squares. *Reliability Engineering and System Safety*, 96(3):398–402, 2011.
- [2] A. Moseleh, K. N. Fleming, G. W. Parry, H. M. Paula, D. H. Worledge, and D. M. Rasmuson. Procedures for treating common cause failures in safety and reliability studies: Procedural framework and examples. Technical Report NUREG/CR-4780, PLG Inc., Newport Beach, CA (USA), January 1988.
- [3] Peter Walley. *Statistical Reasoning with Imprecise Probabilities*. Chapman and Hall, London, 1991.
- [4] Peter Walley. Inferences from multinomial data: Learning about a bag of marbles. *Journal of the Royal Statistical Society, Series B*, 58(1):3–34, 1996.