

## Linear programming under vacuous and possibilistic uncertainty

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### Abstract

Consider the following (standard) linear programming problem: maximise a real-valued linear function  $C^T x$  defined for optimisation variables  $x$  in  $\mathbb{R}^n$  that have to satisfy the constraints  $Ax \leq B$ ,  $x \geq 0$ , where the matrices  $A$ ,  $B$ , and  $C$  are independent random variables that take values  $a$ ,  $b$ , and  $c$  in  $\mathbb{R}^{m \times n}$ ,  $\mathbb{R}^m$  and  $\mathbb{R}^n$ , respectively. Using an approach we developed in previous work [3], the problem is first reduced to a constrained optimisation problem (co-problem) from which the uncertainties present in the description of the constraint are eliminated. The goal is to derive efficient solution techniques for this resulting co-problem.

We investigate what results can be obtained for two types of uncertainty models for the random variables  $A$ ,  $B$ , and  $C$  – vacuous previsions and possibility distributions [see, e.g., 1, 5] – and for two different optimality criteria – maximinity and maximality [see, e.g., 4]. In our poster, we will present the problem description and show illustrated solutions for the most interesting cases we have investigated. We consider three variants of our problem: (i) when there is no uncertainty about  $C$  (this exactly fits the approach in [3]), (ii) when there is no uncertainty about  $B$ , which reduces to variant (i) when considering the dual, and (iii) the general case, which we can convert to the following problem: maximise the real value  $\lambda$  such that  $Ax \leq B$ ,  $C^T x \geq \lambda$  and  $x \geq 0$ , and which is the subject of current research. We here focus on variant (i).

For the different cases we studied, the co-problem and solution techniques derived are:

- Vacuous model relative to a set  $\mathcal{A} \subseteq \mathbb{R}^{m \times n} \times \mathbb{R}^m$ :
  - The maximin solution  $x_m$  can be found by solving the linear programming problem  $\operatorname{argmax}_{x \in \mathbb{I}} c^T x$ , where  $\mathbb{I} := \bigcap_{(a,b) \in \mathcal{A}} \{x \in \mathbb{R}^n : ax \leq b\}$  is the inner feasibility space.
  - The maximal solutions can be found by vertex enumeration [see, e.g., 2] of  $\{x \in \mathbb{R}^n : x \in \mathbb{O} \text{ and } c^T x \geq c^T x_m\}$ , where  $\mathbb{O} := \bigcup_{(a,b) \in \mathcal{A}} \{x \in \mathbb{R}^n : ax \leq b\}$  is the outer feasibility space, which turns out to be convex.
- Possibility distribution  $\pi$  on  $\mathbb{R}^{m \times n} \times \mathbb{R}^m$  with corresponding lower probability  $\underline{P}_\pi$ :
  - The maximin solution is given by  $\operatorname{argmax}_{x \in \mathbb{R}^n} (c^T x - L) \underline{P}_\pi(Ax \leq B)$  where  $L$  is a penalty for violating the constraints. When the possibility distribution  $\pi$  is unimodal then  $(c^T x - L) \underline{P}_\pi(Ax \leq B)$  is unimodal too because of the linearity of the objective function, which allows us to find the maximin solution using a bisection method in which each step a linear programming problem must be solved.
  - We have not yet found an efficient way to calculate the maximal solutions. We can approximate the solutions when  $m$  and  $n$  are small enough.

**Keywords.** linear programming, maximinity, maximality, vacuous prevision, possibility distribution.

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